

**The Attralucian Essays:**  
Exploring the Finite



First Edition

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# The Attralucian Essays



Kolmogorov Complexity: A Geofinitist  
Reinterpretation

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# **Kolmogorov Complexity: A Geofinitist Reinterpretation**

## **Overview**

Kolmogorov complexity provides a foundational notion of information content: the length of the shortest program that produces a given object. Formally elegant and deeply influential, it underpins areas ranging from data compression to machine learning. However, it is also uncomputable in the general case, placing it beyond direct operational use.

This paper does not attempt to resolve that uncomputability. Instead, it reframes the concept within a Geofinitist framework, where all quantities are finite, measured, and accompanied by uncertainty. In this view, Kolmogorov complexity is replaced not by an exact value, but by a bounded, reproducible interval derived from compression procedures, statistical models, and resource constraints.

## **Classical Definition and Limitation**

For a string  $x \in \Sigma^*$  and a universal Turing machine  $U$ , Kolmogorov complexity is defined as:

$$K_U(x) = \min\{|p| : U(p) = x\}.$$

This definition captures the minimal description length

of  $x$ . A fundamental result, however, is that  $K_U(x)$  is uncomputable: no algorithm can determine the shortest program for arbitrary  $x$ , a consequence of the Halting Problem.

Despite this, the theory provides powerful insights. It is invariant up to an additive constant across universal machines and serves as a conceptual benchmark for compression. Yet, as a measurable quantity, it remains inaccessible.

## **A Measured Perspective**

In practice, one never computes  $K_U(x)$ . Instead, one constructs:

- **Upper bounds** via compression algorithms,
- **Lower bounds** via entropy estimates or incompressibility tests.

Geofinitism formalises this practical reality. Rather than treating  $K_U(x)$  as an unattainable exact value, it introduces a measured surrogate: a bounded interval derived from reproducible procedures under finite constraints.

## **Geofinitist Principles Applied**

### **1. Computation as a Resource-Bounded Process**

Program search is not infinite but constrained by budgets in time, memory, and energy. Complexity is defined

relative to these bounds.

## **2. Measurement and Uncertainty**

Program length, runtime, and output correctness are measured quantities:

$$|p| \pm \varepsilon_p, \quad T \pm \varepsilon_T, \quad y \pm \varepsilon_y.$$

## **3. Layered Structure**

Descriptions span multiple layers: encoding schemes, interpreters, and execution environments. These contribute to total description length and variability.

## **4. Useful Fiction**

The exact  $K_U(x)$  is a limiting construct. Its practical role is as a reference point for bounding procedures.

## **5. Finite Constraints**

All measurements occur under finite computational budgets, replacing infinite search with bounded exploration.

## **Measured Kolmogorov Complexity**

Let  $U$  be a fixed reference machine with provenance  $P_U$ . Define a measured execution:

$$\text{Run}_U(p) = (y, \varepsilon_y, P_U; T, \varepsilon_T; S, \varepsilon_S).$$

For tolerance  $\tau$  and resource budget  $B = (T_{\max}, S_{\max})$ , define:

$$K_{U,\tau,B}^{\mathbb{M}}(x) = \min \left\{ |p| : d_{\mathbb{M}}(\text{Run}_U(p), x) \leq \tau, \text{resources} \leq B \right\}.$$

This defines a *measured description length* rather than an exact minimum.

## Finite Invariance

For admissible machines  $U$  and  $V$ :

$$|K_{U,\tau,B}^{\mathbb{M}}(x) - K_{V,\tau',B'}^{\mathbb{M}}(x)| \leq c_{UV} \pm \varepsilon_{UV},$$

where  $c_{UV}$  reflects encoding overhead and  $\varepsilon_{UV}$  captures measurement variability.

Thus invariance becomes a bounded empirical property.

## Operational Bounds

**Upper Bounds.** Given a compressor  $C$ :

$$K^{\mathbb{M}}(x) \leq L_C(x) + c_{C \rightarrow U} \pm \varepsilon_C.$$

**Lower Bounds.** Using empirical entropy:

$$K^{\mathbb{M}}(x) \gtrsim |x| \cdot \hat{H}_k(x) - \text{pen}_k \pm \varepsilon_{\text{fit}}.$$

## **Two-Part Codes and MDL**

For a model class  $\mathcal{M}$ :

$$\text{MDL}_{\mathcal{M}}(x) = \min_{m \in \mathcal{M}} (L(m) + L(x|m)).$$

This provides a finite surrogate:

$$K^{\mathbb{M}}(x) \approx \text{MDL}_{\mathcal{M}}(x) \pm \varepsilon_{\mathcal{M}}.$$

## **Robust (Smoothed) Complexity**

Define:

$$K_{\eta}^{\mathbb{M}}(x) = \mathbb{E}[K^{\mathbb{M}}(\mathbf{P}_{\eta}(x))].$$

Stability under perturbation distinguishes structural simplicity from brittle encodings.

## **Comparison with Abstention**

Define:

$$\Delta K = K^{\mathbb{M}}(x) - K^{\mathbb{M}}(y).$$

Decide only when  $|\Delta K|$  exceeds uncertainty thresholds; otherwise report indeterminacy.

## **Interpretation**

Kolmogorov complexity becomes an operational protocol:

- upper bounds from compressors,
- lower bounds from statistical models,
- uncertainty from measurement and variability,
- decisions based on reproducible margins.

The classical quantity  $K_U(x)$  remains a limiting ideal. The practically meaningful object is the *measured description length interval*.

## **Conclusion**

Kolmogorov complexity is not replaced but finitised. Its uncomputability remains in the asymptotic limit, but within finite regimes it yields to a structured, measurable framework.

This transformation aligns theory with practice: information content is no longer an inaccessible minimum, but a reproducible, bounded quantity grounded in real computation.